Equivalence between Gaussian averaged neutrino oscillations and neutrino decoherence

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In this paper, we show that a Gaussian averaged neutrino oscillation model is equivalent to a neutrino decoherence model. Without loss of generality, the analysis is performed with two neutrino flavors. We also estimate the damping (or decoherence) parameter for atmospheric neutrinos and compare it to earlier obtained results.

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I. INTRODUCTION

In this paper, we investigate two different models for transitions of neutrinos and how they are related to each other. The two models are: neutrino oscillations and neutrino decoherence. Neutrino oscillation models have been the standard description for neutrino transitions so far and still are. Neutrino decoherence models, on the other hand, have recently been discussed by several authors [1–8] as an alternative description to neutrino oscillation models. There exist also other plausible descriptions of neutrino transitions such as neutrino decay models, which have been suggested by Barger et al. [9–12]. However, these models will not be discussed in this paper.

The paper is organized as follows: In Sec. II, we go through the formalisms of neutrino oscillations and neutrino decoherence. In Sec. III, we give the condition for them to be equivalent with each other and we also try to estimate the decoherence term and in Sec. IV, we estimate the damping or decoherence parameter for atmospheric neutrinos. Finally, in Sec. V, we present the summary and also our conclusions.

II. FORMALISM

A. Neutrino oscillations

The theory of neutrino oscillations is the far most plausible description of neutrino transitions. Neutrino oscillations between different neutrino flavors, ν_{α} and ν_{β} , occur with the well-known neutrino transition probabilities

$$P_{\alpha\beta} \equiv P_{\alpha\beta}(L, E) = \delta_{\alpha\beta} - 4 \sum_{\substack{a=1 \ b=1}}^{n} \sum_{b=1}^{n} \Re(U_{\alpha a}^* U_{\beta a} U_{\alpha b} U_{\beta b}^*) \sin^2 \frac{\Delta m_{ab}^2 L}{4E}$$
$$- 2 \sum_{\substack{a=1 \ b=1}}^{n} \sum_{b=1}^{n} \Im(U_{\alpha a}^* U_{\beta a} U_{\alpha b} U_{\beta b}^*) \sin \frac{\Delta m_{ab}^2 L}{2E}, \quad \alpha, \beta = e, \mu, \tau, \dots,$$
(1)

where $\delta_{\alpha\beta}$ is Kronecker's delta, L is the neutrino path length, E is the neutrino energy, n is the number of neutrino flavors, $\Delta m_{ab}^2 \equiv m_a^2 - m_b^2$, $a, b = 1, 2, \dots, n$ is the (vacuum) mass squared difference between different neutrino mass

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eigenstates ν_a and ν_b (or rather $|\nu_a\rangle$ and $|\nu_b\rangle$) with masses m_a and m_b , respectively, and

$$U = (U_{\alpha a}) = \begin{pmatrix} U_{e1} & U_{e2} & U_{e3} & \cdots \\ U_{\mu 1} & U_{\mu 2} & U_{\mu 3} & \cdots \\ U_{\tau 1} & U_{\tau 2} & U_{\tau 3} & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

is the unitary $n \times n$ Maki–Nakagawa–Sakata (MNS) mixing matrix [13], which relates the flavor states $|\nu_{\alpha}\rangle$ ($\alpha = e, \mu, \tau, \ldots$) and the mass eigenstates $|\nu_{a}\rangle$ ($a = 1, 2, \ldots, n$).

However, since in practice a neutrino wave is neither detected nor produced with sharp energy or with well-defined propagation length, we have to average over the L/E dependence and other uncertainties in the detection and emission of the neutrino wave.

We will here use the Gaussian average, which is defined by

$$\langle P \rangle \equiv \int_{-\infty}^{\infty} P(x)f(x) dx,$$
 (2)

where

$$f(x) \equiv \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\ell)^2}{2\sigma^2}}.$$

Here $\ell \equiv \langle x \rangle$ and $\sigma \equiv \sqrt{\langle (x - \langle x \rangle)^2 \rangle}$ are the expectation value and standard deviation, respectively.

By taking the Gaussian average of Eq. (1) and using $x \equiv \frac{L}{4E}$, we obtain the averaged transition probabilities from ν_{α} to ν_{β} as

$$\langle P_{\alpha\beta} \rangle = \delta_{\alpha\beta} - 2 \sum_{\substack{a=1 \ b=1 \ a < b}}^{n} \sum_{b=1}^{n} \Re(U_{\alpha a}^{*} U_{\beta a} U_{\alpha b} U_{\beta b}^{*}) \left(1 - \cos\left(2\ell \Delta m_{ab}^{2}\right) e^{-2\sigma^{2}(\Delta m_{ab}^{2})^{2}} \right)$$

$$- 2 \sum_{\substack{a=1 \ b=1 \ a < b}}^{n} \sum_{b=1}^{n} \Im(U_{\alpha a}^{*} U_{\beta a} U_{\alpha b} U_{\beta b}^{*}) \sin\left(2\ell \Delta m_{ab}^{2}\right) e^{-2\sigma^{2}(\Delta m_{ab}^{2})^{2}}, \quad \alpha, \beta = e, \mu, \tau, \dots$$
(3)

The physical interpretations of the parameters ℓ and σ are the following:

• The parameter ℓ : The parameter ℓ deals with the sensitivity of an experiment and is given by $\ell \equiv \langle L/E \rangle/4$. Note that we will here use $\langle L/E \rangle = \langle L \rangle/\langle E \rangle$, *i.e.*,

$$\ell = \frac{\langle L \rangle}{4 \langle E \rangle}.\tag{4}$$

This simplification holds if L and E are independent.

• The parameter σ : The parameter σ is a so-called damping factor, which is responsible for the damping of the neutrino oscillation probabilities.

A pessimistic upper bound for the damping parameter σ is given by the uncertainty in x, *i.e.*,

$$\sigma \simeq \Delta x = \Delta \frac{L}{4E} \le \left| \frac{\partial x}{\partial L} \right|_{L = \langle L \rangle, E = \langle E \rangle} \Delta L + \left| \frac{\partial x}{\partial E} \right|_{L = \langle L \rangle, E = \langle E \rangle} \Delta E = \frac{\langle L \rangle}{4 \langle E \rangle} \left(\frac{\Delta L}{\langle L \rangle} + \frac{\Delta E}{\langle E \rangle} \right), \tag{5}$$

where ΔL and ΔE are the uncertainties in the neutrino path length and the neutrino energy, respectively. A more optimistic upper bound would be

$$\sigma \lesssim \frac{\langle L \rangle}{4\langle E \rangle} \sqrt{\left(\frac{\Delta L}{\langle L \rangle}\right)^2 + \left(\frac{\Delta E}{\langle E \rangle}\right)^2}.$$
 (6)

For large values of σ , the dependence on the mass squared differences will be completely washed out, since $1-\cos\left(2\ell\Delta m_{ab}^2\right)e^{-2\sigma^2(\Delta m_{ab}^2)^2}\to 1$ and $\sin\left(2\ell\Delta m_{ab}^2\right)e^{-2\sigma^2(\Delta m_{ab}^2)^2}\to 0$ when $\sigma\to\infty$, and the Gaussian

averaged transition probabilities $\langle P_{\alpha\beta} \rangle$ will just be dependent on the MNS mixing matrix elements, the $U_{\alpha a}$'s, *i.e.*,

$$\lim_{\sigma \to \infty} \langle P_{\alpha\beta} \rangle = \delta_{\alpha\beta} - 2 \sum_{a=1}^{n} \sum_{b=1}^{n} \Re(U_{\alpha a}^* U_{\beta a} U_{\alpha b} U_{\beta b}^*). \tag{7}$$

Note that the imaginary part sum (the second sum in Eq. (3)) does not appear at all (in any form) in Eq. (7). Equation (7) corresponds to the classical limit.

In the other limit, $\sigma \to 0$, we will just regain Eq. (1) from Eq. (3) with $\ell = x$, i.e.,

$$\lim_{\alpha \to 0} \langle P_{\alpha\beta} \rangle = P_{\alpha\beta}. \tag{8}$$

In the case of two neutrino flavors (n = 2), we can call these neutrino flavors ν_e and ν_{μ} , the unitary (orthogonal) 2×2 MNS mixing matrix U is usually parameterized as

$$U = (U_{\alpha a}) = \begin{pmatrix} U_{e1} & U_{e2} \\ U_{\mu 1} & U_{\mu 2} \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}, \tag{9}$$

where θ is the (vacuum) mixing angle. Note that $U^* = U$ in this case. Furthermore, $\Delta m^2 \equiv \Delta m_{21}^2 = -\Delta m_{12}^2$. Observe that for two neutrino flavors there cannot be any \mathcal{CP} (or \mathcal{T}) violation in the MNS mixing matrix U, since U is a real matrix in this case, which means that

$$P_{ee} = 1 - P_{e\mu} = 1 - P_{\mu e} = P_{\mu\mu}. (10)$$

By taking the average of Eq. (10), we of course also have

$$\langle P_{ee} \rangle = 1 - \langle P_{e\mu} \rangle = 1 - \langle P_{\mu e} \rangle = \langle P_{\mu \mu} \rangle.$$
 (11)

Thus, inserting $\alpha = e$, $\beta = \mu$, and n = 2 into Eq. (3), we obtain the Gaussian averaged two flavor neutrino oscillation formula as

$$\langle P_{e\mu}\rangle(\ell) = \frac{1}{2}\sin^2 2\theta \left(1 - e^{-2\sigma^2(\Delta m^2)^2}\cos\left(2\ell\Delta m^2\right)\right),\tag{12}$$

where $\ell \simeq \langle L \rangle / (4 \langle E \rangle)$, i.e.,

$$\langle P_{e\mu} \rangle (\langle L \rangle, \langle E \rangle) = \frac{1}{2} \sin^2 2\theta \left(1 - e^{-2\sigma^2 \left(\Delta m^2 \right)^2} \cos \frac{\Delta m^2 \langle L \rangle}{2 \langle E \rangle} \right). \tag{13}$$

In what follows, we will use $\langle P_{\alpha\beta} \rangle = P_{\alpha\beta}$, $\langle L \rangle = L$, and $\langle E \rangle = E$ for simplicity.

B. Neutrino decoherence

Neutrino decoherence arises when we consider a neutrino system to be coupled to an environment (or a reservoir or a bath). In general, we are not allowed to use the Schrödinger equation to describe system-environment type interactions, since even if we start initially with a pure quantum mechanical state, the coupling to the environment will produce mixed quantum mechanical states. Thus, we are forced to use the Liouville equation.

Assume that $\rho = \rho(t)$ is the neutrino density matrix [21], which is Hermitian $(\rho^{\dagger} = \rho)$ with positive eigenvalues and has constant trace equal to one (tr $\rho = 1$). The Liouville equation for the neutrino density matrix is then

$$\dot{\rho} = -i \left[H_m, \rho \right], \tag{14}$$

where H_m is the free Hamiltonian for the neutrinos in the mass eigenstate basis. We will assume that the neutrino system is a two-level system, *i.e.*, we have two neutrino flavors (n=2), ν_e and ν_μ , as in the neutrino oscillation formalism. Thus, in this case, the neutrino density matrix ρ is a 2×2 matrix and the free Hamiltonian H_m is also a 2×2 matrix and is given by

$$H_m = \frac{1}{2E} \operatorname{diag}(m_1^2, m_2^2) \quad \text{or} \quad H_m \mapsto H_m' = H_m - \frac{1}{2} (\operatorname{tr} H_m) I_2 = \frac{1}{4E} \operatorname{diag}(-\Delta m^2, \Delta m^2),$$
 (15)

where I_2 is the 2×2 identity matrix and again $\Delta m^2 \equiv m_2^2 - m_1^2$. The traceless Hamiltonian H'_m can be used instead of the Hamiltonian H_m , since they just differ by a trace (of any of them). This trace will only give rise to a global phase that will not affect the transition probabilities anyway and is therefore irrelevant.

Furthermore, note that we will not consider matter effects in this paper. In the case of neutrino transitions in matter, the Hamiltonian has a much more complicated structure.

Solving Eq. (14) under the above assumptions leads to the ordinary neutrino oscillation transition probabilities in Eq. (1) with n=2 as it should. However, the neutrinos could be influenced by so-called decoherence effects. Such effects are introduced by an extra term $\mathcal{D}[\rho]$ in the Liouville equation for the neutrinos, *i.e.*, the Markovian Liouville–Lindblad quantum mechanical master equation [2, 14, 15]

$$\dot{\rho} = -i\left[H_m, \rho\right] - \mathcal{D}[\rho],\tag{16}$$

which allows transitions from pure quantum mechanical states to mixed quantum mechanical states. We will here use the Lindblad form for the decoherence term [14], viz.,

$$\mathcal{D}[\rho] = \sum_{a=1}^{n} \left(\left\{ \rho, D_a^{\dagger} D_a \right\} - 2D_a \rho D_a^{\dagger} \right), \tag{17}$$

where the D_a 's are Lindblad operators [22] arising from tracing or averaging away environment dynamics and must be such that $\sum_{a=1}^{n} D_a^{\dagger} D_a$ is a well-defined 2×2 matrix. Note that the extra term $\mathcal{D}[\rho]$ is responsible for the fact that the quantum mechanical states can develop dissipation and irreversibility, and possible loss of quantum coherence *i.e.*, (quantum) decoherence [2, 16]. The D_a 's are normally Hermitian ($D_a^{\dagger} = D_a$) if we require monotone time increase of the von Neumann entropy, $S = -\text{tr}(\rho \log \rho)$, and they usually also commute with the Hamiltonian ($[H_m, D_a] = 0$) if we require conservation of the statistical average of the energy, *i.e.*, $\frac{d}{dt}\text{tr}(H_m\rho) = 0$.

Assuming that the D_a 's are Hermitian, Eq. (17) becomes

$$\mathcal{D}[\rho] = \sum_{a=1}^{n} [D_a, [D_a, \rho]] = \sum_{a=1}^{n} (\rho D_a^2 + D_a^2 \rho - 2D_a \rho D_a).$$
 (18)

The operators ρ , H_m , D_a , which are all Hermitian, can therefore be expanded in the Pauli matrix basis as

$$\rho = \frac{1}{2} \left(I_2 + \mathbf{p} \cdot \boldsymbol{\sigma} \right), \tag{19}$$

$$H_m = \frac{1}{2} \mathbf{k} \cdot \boldsymbol{\sigma},\tag{20}$$

$$D_a = \frac{1}{2} \mathbf{d}_a \cdot \boldsymbol{\sigma}, \quad a = 1, 2, \dots, n, \tag{21}$$

where I_2 is again the 2×2 identity matrix, $\boldsymbol{\sigma} \equiv (\sigma_1, \sigma_2, \sigma_3)$ is the Pauli matrix vector, and $\mathbf{k} \equiv (0, 0, -k)$. Here $k \equiv \frac{\Delta m^2}{2E}$. In the Pauli matrix basis, we have after some tedious calculations

$$\dot{\rho} = \frac{1}{2}\dot{\mathbf{p}}\cdot\boldsymbol{\sigma},\tag{22}$$

$$[H_m, \rho] = \frac{i}{2} (\mathbf{k} \times \mathbf{p}) \cdot \boldsymbol{\sigma}, \tag{23}$$

$$\mathcal{D}[\rho] = \frac{1}{2} \sum_{a=1}^{n} (|\mathbf{d}_a|^2 \mathbf{p} \cdot \boldsymbol{\sigma} - (\mathbf{d}_a \cdot \mathbf{p})(\mathbf{d}_a \cdot \boldsymbol{\sigma})), \qquad (24)$$

which means that Eq. (16) can be written in the form

$$\dot{\mathbf{p}} \cdot \boldsymbol{\sigma} = (\mathbf{k} \times \mathbf{p}) \cdot \boldsymbol{\sigma} - \sum_{a=1}^{n} (|\mathbf{d}_{a}|^{2} \mathbf{p} \cdot \boldsymbol{\sigma} - (\mathbf{d}_{a} \cdot \mathbf{p})(\mathbf{d}_{a} \cdot \boldsymbol{\sigma})).$$
 (25)

Using well-known formulas from vector algebra, the sum in the above equation can be expressed as

$$\sum_{a=1}^{n} (\mathbf{d}_a \times (\mathbf{d}_a \times \mathbf{p})) \cdot \boldsymbol{\sigma}.$$

Thus, we have

$$\dot{\mathbf{p}} \cdot \boldsymbol{\sigma} = (\mathbf{k} \times \mathbf{p}) \cdot \boldsymbol{\sigma} - \sum_{a=1}^{n} (\mathbf{d}_{a} \times (\mathbf{d}_{a} \times \mathbf{p})) \cdot \boldsymbol{\sigma}$$
(26)

or

$$\dot{\mathbf{p}} = \mathbf{k} \times \mathbf{p} - \sum_{a=1}^{n} \mathbf{d}_a \times (\mathbf{d}_a \times \mathbf{p}) = \mathbf{k} \times \mathbf{p} - \left(\sum_{a=1}^{n} |\mathbf{d}_a|^2\right) \mathbf{p} + \sum_{a=1}^{n} (\mathbf{d}_a \cdot \mathbf{p}) \mathbf{d}_a, \tag{27}$$

which is the Bloch–Lindblad equation. The first term after the second equality sign in the Bloch–Lindblad equation, $\mathbf{k} \times \mathbf{p}$, is giving rise to neutrino oscillations, whereas the second and third terms are the decoherence terms.

If $[H_m, D_a] = 0$, then it follows that $\mathbf{k} \times \mathbf{d}_a = \mathbf{0}$, *i.e.*, \mathbf{k} and \mathbf{d}_a are parallel vectors. Thus, we can put $\mathbf{d}_a = d_a \hat{\mathbf{k}}$, where $\hat{\mathbf{k}} \equiv \mathbf{k}/|\mathbf{k}|$. Inserting this into Eq. (27), we obtain

$$(\dot{p}_1, \dot{p}_2, \dot{p}_3) = (kp_2, -kp_1, 0) - d^2(p_1, p_2, p_3) + (0, 0, d^2p_3), \tag{28}$$

where $d^2 \equiv \sum_{a=1}^n d_a^2$, i.e.,

$$\dot{p}_1 = kp_2 - d^2p_1, \tag{29}$$

$$\dot{p}_2 = -kp_1 - d^2p_2,\tag{30}$$

$$\dot{p}_3 = 0, \tag{31}$$

which can be written in matrix form as $(\dot{\mathbf{p}} = M\mathbf{p})$

$$\begin{pmatrix} \dot{p}_1 \\ \dot{p}_2 \\ \dot{p}_3 \end{pmatrix} = \begin{pmatrix} -d^2 & k & 0 \\ -k & -d^2 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} p_1 \\ p_2 \\ p_3 \end{pmatrix}. \tag{32}$$

This system of first order differential equations has the solution

$$\mathbf{p}(t) \equiv \begin{pmatrix} p_1(t) \\ p_2(t) \\ p_3(t) \end{pmatrix} = \begin{pmatrix} e^{-d^2t} \cos kt & e^{-d^2t} \sin kt & 0 \\ -e^{-d^2t} \sin kt & e^{-d^2t} \cos kt & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} p_1(0) \\ p_2(0) \\ p_3(0) \end{pmatrix} \equiv e^{Mt} \mathbf{p}(0), \tag{33}$$

i.e.,

$$p_1(t) = p_1(0)e^{-d^2t}\cos kt + p_2(0)e^{-d^2t}\sin kt,$$
(34)

$$p_2(t) = -p_1(0)e^{-d^2t}\sin kt + p_2(0)e^{-d^2t}\cos kt,$$
(35)

$$p_3(t) = p_3(0). (36)$$

Another, but equivalent, way of obtaining Eq. (27) has been found by Stodolsky. Stodolsky's formula is given by [17, 18]

$$\dot{\mathbf{P}} = \mathbf{V} \times \mathbf{P} - D\mathbf{P}_{\mathrm{T}},\tag{37}$$

where \mathbf{P} is the "polarization vector", \mathbf{V} is the "magnetic field", D is the damping parameter determined by the scattering amplitudes on the background (i.e., the environment), and \mathbf{P}_{T} is the "transverse" part of \mathbf{P} . In a two-level system, the length of \mathbf{P} measures the degree of coherence: $|\mathbf{P}|=1$ corresponds to a pure state, $0<|\mathbf{P}|<1$ to some degree of incoherence, and $|\mathbf{P}|=0$ to the completely mixed or incoherent state [17], i.e., the loss of coherence is given by the shrinking of $|\mathbf{P}|$. The time evolution described by Eq. (37) is a precession around \mathbf{V} , combined with the shrinking of $|\mathbf{P}|$ to zero. The final state corresponds to $\rho=\frac{1}{2}$, where both neutrino flavor states, ν_e and ν_μ , are equally populated, and with vanishing coherence between them. In our notation, $\mathbf{P}\equiv\mathbf{p}$, $\mathbf{V}\equiv\mathbf{k}$, and $D\mathbf{p}_{\mathrm{T}}\equiv\left(\sum_{a=1}^{n}|\mathbf{d}_a|^2\right)\mathbf{p}-\sum_{a=1}^{n}(\mathbf{d}_a\cdot\mathbf{p})\mathbf{d}_a=d^2(\mathbf{p}-(\mathbf{p}\cdot\hat{\mathbf{k}})\hat{\mathbf{k}})$. Since here $\hat{\mathbf{k}}=-\mathbf{e}_z$, we have that $D\mathbf{P}_{\mathrm{T}}=d^2(\mathbf{p}-p_3\mathbf{e}_z)=d^2(p_1,p_2,0)$.

Thus, we can now construct the time-dependent neutrino density matrix as

$$\rho(t) = \frac{1}{2} \left(I_2 + \mathbf{p}(t) \cdot \boldsymbol{\sigma} \right) = \frac{1}{2} \begin{pmatrix} 1 + p_3(t) & p_1(t) - ip_2(t) \\ p_1(t) + ip_2(t) & 1 - p_3(t) \end{pmatrix}.$$
(38)

As usual, the neutrino flavor states $|\nu_{\alpha}\rangle$, where $\alpha = e, \mu$, are superpositions of the neutrino mass eigenstates $|\nu_{\alpha}\rangle$, where a = 1, 2, i.e.,

$$|\nu_{\alpha}\rangle = \sum_{a=1}^{2} U_{\alpha a}^{*} |\nu_{a}\rangle = \sum_{a=1}^{2} U_{\alpha a} |\nu_{a}\rangle, \quad \alpha = e, \mu.$$
(39)

If we represent the mass eigenstates by the vectors $|\nu_1\rangle=(1,0)$ and $|\nu_2\rangle=(0,1)$, then the flavor states become $|\nu_e\rangle=(\cos\theta,\sin\theta)$ and $|\nu_\mu\rangle=(-\sin\theta,\cos\theta)$. Furthermore, if we assume that the initial state of a neutrino is $|\nu_e\rangle$, i.e., the system is prepared in a pure ν_e state, then the initial condition for the neutrino density matrix is

$$\rho(0) \equiv \rho_{ee} \equiv |\nu_e\rangle\langle\nu_e| = \begin{pmatrix} \cos^2\theta & \sin\theta\cos\theta\\ \sin\theta\cos\theta & \cos^2\theta \end{pmatrix} = \frac{1}{2}\left(I_2 + \mathbf{p}(0)\cdot\boldsymbol{\sigma}\right),\tag{40}$$

and it follows, using Eq. (38), that $p_1(0) = \sin 2\theta$, $p_2(0) = 0$, and $p_3(0) = \cos 2\theta$. Similarly, if the initial state is $|\nu_{\mu}\rangle$, then we have

$$\rho_{\mu\mu} \equiv |\nu_{\mu}\rangle\langle\nu_{\mu}| = \begin{pmatrix} \sin^2\theta & -\sin\theta\cos\theta \\ -\sin\theta\cos\theta & \cos^2\theta \end{pmatrix} = 1 - \rho_{ee}. \tag{41}$$

Thus, the neutrino transition probabilities with decoherence effects read

$$P_{ee}(t) \equiv \operatorname{tr}(|\nu_e\rangle\langle\nu_e|\rho(t)) = \frac{1}{2} \left[1 + \sin 2\theta p_1(t) + \cos 2\theta p_3(t)\right], \tag{42}$$

$$P_{e\mu}(t) \equiv \text{tr}(|\nu_{\mu}\rangle\langle\nu_{\mu}|\rho(t)) = \frac{1}{2} [1 - \sin 2\theta p_1(t) - \cos 2\theta p_3(t)].$$
 (43)

Moreover, as in the neutrino oscillation formalism, we have the relation between the transition probabilities

$$P_{e\mu}(t) = 1 - P_{ee}(t) = 1 - P_{\mu\mu}(t) = P_{\mu e}(t), \tag{44}$$

since

$$1 = \operatorname{tr} \rho(t) = \operatorname{tr} (1\rho(t)) = \operatorname{tr} \left(\sum_{\alpha = e, \mu} |\nu_{\alpha}\rangle\langle\nu_{\alpha}|\rho(t) \right) = \operatorname{tr} (|\nu_{e}\rangle\langle\nu_{e}|\rho(t)) + \operatorname{tr} (|\nu_{\mu}\rangle\langle\nu_{\mu}|\rho(t)) = P_{ee}(t) + P_{e\mu}(t). \tag{45}$$

Inserting Eqs. (34) - (36) with the above initial conditions into Eq. (43) gives

$$P_{e\mu}(t) = \frac{1}{2}\sin^2 2\theta \left(1 - e^{-d^2t}\cos kt\right). \tag{46}$$

Furthermore, inserting $t \simeq L$ and $k = \Delta m^2/(2E)$, we thus obtain the neutrino decoherence formula for two neutrino flavors as

$$P_{e\mu}(L,E) = \frac{1}{2}\sin^2 2\theta \left(1 - e^{-d^2L}\cos\frac{\Delta m^2L}{2E}\right). \tag{47}$$

When $\Delta m^2 = 0$ (no neutrino oscillations), we find the pure neutrino decoherence formula

$$P_{e\mu}(L) = \frac{1}{2}\sin^2 2\theta \left(1 - e^{-d^2L}\right). \tag{48}$$

Note that this formula is explicitly independent of the neutrino energy E. Other interesting limits are obtained when d=0 (no neutrino decoherence)

$$P_{e\mu}(L,E) = \frac{1}{2}\sin^2 2\theta \left(1 - \cos\frac{\Delta m^2 L}{2E}\right),\tag{49}$$

i.e., the well-known Pontecorvo neutrino oscillation formula (cf. Eq. (8)) and when $d \to \infty$ (or $\Delta m^2 \gg 2E/L$)

$$P_{e\mu} = \frac{1}{2}\sin^2 2\theta,\tag{50}$$

i.e., the classical transition probability formula (cf. Eq. (7)), which is independent of both the neutrino path length L and the neutrino energy E. The effects of both neutrino oscillations and neutrino decoherence are said to be completely washed out.

III. EQUIVALENCE BETWEEN THE TWO MODELS

In the previous section, we have seen that the two formalisms, neutrino oscillations and neutrino decoherence, have the same dependence for the transition probabilities. In both scenarios, the oscillation factor $\cos \frac{\Delta m^2 L}{2E}$ is damped by an exponential factor $(e^{-2\sigma^2(\Delta m^2)^2})$ or e^{-d^2L} .

Comparing Eqs. (13) and (47) with each other, we obtain

$$2\sigma^2 \left(\Delta m^2\right)^2 = d^2 L,\tag{51}$$

i.e., the decoherence parameter d is related to the damping parameter σ as

$$d = \frac{\sqrt{2\Delta}m^2}{\sqrt{L}}\sigma,\tag{52}$$

which means that the two investigated models must be equivalent if this condition is fulfilled. The units of the decoherence parameter d is $[d] = eV^{1/2}$. This investigation could of course be extended to n neutrino flavors, but we will not do this here.

Next, we will now try to estimate the decoherence term $\mathcal{D}[\rho]$ (or the decoherence parameter d). The damping parameter σ can be written as

$$\sigma = \frac{L}{4E}r, \quad \text{where } r = \frac{\Delta L}{L} + \frac{\Delta E}{E} \text{ (pessimistic) or } r = \sqrt{\left(\frac{\Delta L}{L}\right)^2 + \left(\frac{\Delta E}{E}\right)^2} \text{ (optimistic)}. \tag{53}$$

Inserting Eq. (53) into Eq. (52) yields

$$d = \frac{\Delta m^2 \sqrt{L}}{2\sqrt{2}E}r\tag{54}$$

or

$$d^2 = \frac{\left(\Delta m^2\right)^2 L}{8E^2} r^2. \tag{55}$$

Thus, we obtain the following estimate for the decoherence term

$$\mathcal{D} \propto d^2 \sim \frac{\left(\Delta m^2\right)^2 L}{E^2} \tag{56}$$

if we assume that $r^2 = \mathcal{O}(1)$.

Recently, other estimates of the decoherence term $\mathcal{D}[\rho]$ have been found by Lisi *et al.* [3] and Adler [6]. Their different estimates are

$$\mathcal{D} \sim \frac{H_m^2}{M_{\text{Planck}}} \sim \frac{E^2}{M_{\text{Planck}}} \tag{57}$$

and

$$\mathcal{D} \sim \frac{(\Delta H_m)^2}{M_{\text{Planck}}} \sim \frac{\left(\Delta m^2\right)^2}{E^2 M_{\text{Planck}}},\tag{58}$$

respectively, where again $\mathcal{D} \propto d^2$, $H_m \simeq E$, $\Delta H_m \simeq \frac{\Delta m^2}{2E} = k$, and M_{Planck} is the Planck mass scale. They argue that the decoherence could be due to e.g. quantum gravity. We, on the other hand, have here argued more phenomenologically.

In the next section, we are going to estimate the decoherence parameter for atmospheric neutrinos.

IV. ESTIMATION OF THE DECOHERENCE PARAMETER FOR ATMOSPHERIC NEUTRINOS

The path length for atmospheric neutrinos, which is easily obtained from geometrical considerations, is given by

$$L \equiv L(\cos \vartheta) = \sqrt{R_{\oplus}^2 \cos^2 \vartheta + 2R_{\oplus}d + d^2} - R_{\oplus} \cos \vartheta, \tag{59}$$

where ϑ is the zenith angle, R_{\oplus} is the radius of the Earth ($R_{\oplus} \simeq 6400\,\mathrm{km}$), and d is the typical altitude of the production point of atmospheric neutrinos above the surface of the Earth ($d \simeq 10\,\mathrm{km}$). The uncertainty in the path length is mainly determined by $\Delta\cos\vartheta$ and therefore

$$\Delta L = \left| \frac{\partial L(\cos \vartheta)}{\partial \cos \vartheta} \right| \Delta \cos \vartheta = \frac{R_{\oplus} L}{L + R_{\oplus} \cos \vartheta} \Delta \cos \vartheta, \quad i.e., \quad \frac{\Delta L}{L} = \frac{R_{\oplus}}{\sqrt{R_{\oplus}^2 \cos^2 \vartheta + 2R_{\oplus} d + d^2}} \Delta \cos \vartheta. \tag{60}$$

The uncertainty in the neutrino energy for the Super-Kamiokande experiment [19] as well as for the future MONOLITH experiment [20] is of the order of magnitude

$$\Delta E \sim E, \quad i.e., \quad \frac{\Delta E}{E} = \mathcal{O}(1),$$
 (61)

even though the energy resolution is better for the MONOLITH than Super-Kamiokande they are of the same order of magnitude.

Thus, using Eqs. (5), (60), and (61) as well as inserting numerical values, we have the following upper bound for the damping parameter $\sigma_{\rm atm.}$ for up-going (cos $\vartheta = -0.95$ and $\Delta \cos \vartheta = 0.1 \implies L \simeq 12000$ km and $\Delta L/L \simeq 0.11$) atmospheric neutrinos

$$\sigma_{\text{atm.}} \lesssim 3.0 \cdot 10^{-4} \,\text{m/eV} \simeq 6.0 \cdot 10^{-11} \,\text{m}^2 \simeq 1.5 \cdot 10^3 \,\text{eV}^{-2}.$$
 (62)

From two flavor neutrino oscillations analyses of Super-Kamiokande data, assuming ν_{μ} - ν_{τ} oscillations, the atmospheric mass squared difference $\Delta m^2_{\rm atm.}$ has been measured to be $\Delta m^2_{\rm atm.} \simeq 3.2 \cdot 10^{-3} \, \rm eV^2$ (and the mixing angle $\theta_{\rm atm.} \simeq 45^{\circ}$) [19]. This means that the decoherence parameter for atmospheric neutrinos is

$$d_{\text{atm.}} = \frac{\sqrt{2\Delta m_{\text{atm.}}^2}}{\sqrt{L(\cos \vartheta = -0.95)}} \sigma_{\text{atm.}} \lesssim 2.8 \cdot 10^{-8} \,\text{eV}^{1/2}$$
(63)

or

$$d_{\text{atm}}^2 \lesssim 7.9 \cdot 10^{-16} \,\text{eV} = 7.9 \cdot 10^{-25} \,\text{GeV} \sim 10^{-24} \,\text{GeV}.$$
 (64)

Recently, Lisi et al. have discussed three scenarios for the decoherence parameter on the form $d_{\rm atm.}^2 = \gamma_0 \left(\frac{E}{\rm GeV}\right)^n$, where γ_0 is a constant and n=-1,0,2 [3]. Our result is in general agreement with the ones obtained by Lisi et al. (i.e., they are all comparable within some orders of magnitude), which are $d_{\rm atm.}^2 < 0.9 \cdot 10^{-27}$ GeV at 90% C.L. (n=2), $d_{\rm atm.}^2 < 3.5 \cdot 10^{-23}$ GeV at 90% C.L. (n=0), $d_{\rm atm.}^2 < 4.1 \cdot 10^{-23}$ GeV at 95% C.L. (n=0), $d_{\rm atm.}^2 < 5.5 \cdot 10^{-23}$ GeV at 99% C.L. (n=0), and $d_{\rm atm.}^2 < 2 \cdot 10^{-21}$ GeV at 90% (n=-1) [3]. They found that $d_{\rm atm.}^2 \propto E^{-1}$ is favored, which is natural from our point of view, since this would mean that the dependence of the exponentially damping factor in the transition probabilities is on the form $e^{-\alpha L/E}$, where α is some constant, i.e., it is exponentially decreasing with the L/E dependence. They also fitted the data with a pure neutrino decoherence model $(\Delta m_{\rm atm.}^2 = 0)$ and obtained $d_{\rm atm.}^2 = 1.2 \cdot 10^{-21}$ GeV (n=-1) [3]. In all their fits, they obtained maximal mixing, i.e., $\theta_{\rm atm.} = 45^\circ$, as their best fit value.

V. SUMMARY AND CONCLUSIONS

In conclusion, we have shown, in this paper, that a Gaussian averaged neutrino oscillation model and a neutrino decoherence model are equivalent if Eq. (52) is satisfied, i.e., $d = \frac{\sqrt{2}\Delta m^2}{\sqrt{L}}\sigma$. Our upper bound on $d_{\rm atm.}^2 \lesssim 10^{-24}\,{\rm GeV}$ then immediately follows from the results of the Super-Kamiokande analyses, i.e., the neutrino decoherence model is just a reparameterization of the Gaussian averaged neutrino oscillation model or vice versa. We have also estimated the decoherence term to be $\mathcal{D} \propto d^2 \sim \frac{\left(\Delta m^2\right)^2 L}{E^2}$, which is different from earlier results including the Planck mass scale $M_{\rm Planck}$ and motivations that decoherence could be induced by new physics beyond the Standard Model such as e.g. quantum gravity.

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- [21] The complete time evolution of the neutrino density matrix ρ is given by a quantum mechanical semigroup, *i.e.*, by a completely positive, trace-preserving family of linear maps: $\gamma_t : \rho(0) \mapsto \rho(t)$ [2].
- [22] Statements by Adler [6]:
 - 1. For a two-level system, the only choices of D_a that commute with H_m are either $D_a = \delta_a I_2$ (trivial, since it makes no contribution to the decoherence term $\mathcal{D}[\rho]$ [Eq. (18)] and it can therefore be ignored) or $D_a = d_a H_m$.
 - 2. The sum in the decoherence term can be replaced with a single Lindblad operator $D = dH_m$.